## **Mobile Radio Communications**

**Course 3: Radio wave propagation** 



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# **Propagation mechanisms**

- free space propagation
- reflection
- diffraction
- scattering

**LARGE SCALE: average attenuation** 

 $dx >> \lambda$  $dt >> T_s$ 

SMALL SCALE: short-term variations in position and time  $dx \approx \lambda$  $dt \approx T_s$ 



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## Large-scale/small scale variations <u>space</u>





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## Large-scale/small scale variations <u>time</u>





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## **Free-space propagation**

- **P:** power
- G: antenna gain
- *d*: separation distance
- *L*: system loss

$$P_{R}(d) = \frac{P_{T} \cdot G_{T} \cdot G_{R} \cdot \lambda^{2}}{(4\pi)^{2} \cdot d^{2} \cdot L}$$



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## Antenna gain

- isotropic: G=1
- directional:  $G(\theta)$



#### **EIRP: effective isotropic radiated power**

(received power as if received from isotropic source)





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## **Free-space path loss**

$$PL = 10\log\frac{P_T}{P_R}$$
$$= 20\log\frac{4\pi}{\lambda} + 20\log d$$
$$= PL(d_0) + 20\log\frac{d}{d_0}$$

#### attenuation 20 dB/dec



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 $E_{tot} = \frac{\alpha}{d_1} \cos(\omega_c t) + \Gamma \frac{\alpha}{d_2} \cos(\omega_c t + \Delta \theta)$ 



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$$\Delta = d_2 - d_1$$
  
=  $\sqrt{d^2 + (h_t + h_r)^2} - \sqrt{d^2 + (h_t - h_r)^2}$   
 $\approx \frac{2h_t h_r}{d} \qquad d >> h$ 

$$\Delta \theta \approx \frac{4\pi h_t h_r}{\lambda d}$$



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$$E^{2} = \left(\frac{\alpha}{d}\right)^{2} \left\{ \left(1 - \cos \Delta \theta\right)^{2} + \sin^{2} \Delta \theta \right\}$$
$$= \left(\frac{\alpha}{d}\right)^{2} \left(2 - 2\cos 2\Delta \theta\right) \approx \left(\frac{\alpha}{d}\right)^{2} \left(\Delta \theta\right)^{2}$$

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$$E \approx \left(\frac{\alpha}{d}\right) \frac{4\pi h_t h_r}{\lambda d}$$

$$P_r = \left| E \right|^2 \frac{A_e}{120\pi} \approx \beta \frac{\left(h_t h_r\right)^2}{d^4}$$

$$A_e \approx G \frac{\lambda^2}{4\pi}$$



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## **Two-ray path loss model**

 $PL = 40 \log d -$ 

#### $(10\log G_t + 10\log G_r + 20\log h_t + 20\log h_r)$

#### attenuation 40 dB/dec



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#### Path loss exponent





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## Log-distance path loss model

$$\overline{PL} = PL(d_0) + 10n \log \frac{d}{d_0}$$

d: T-R distance

 $d_0$ : close-in reference distance

n: path loss exponent ranging from 1 to 6



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## **Okumura path loss model**

 $L_{50} = L_F + A_{mu}(f, d) - G(h_t) - G(h_r) - G_{AREA}$ 

$$G(h_t) = 20 \log(\frac{h_t}{200}) \qquad 10 \text{m} < h_t < 1000\text{m}$$
$$G(h_r) = 10 \log(\frac{h_r}{3}) \qquad h_r < 3\text{m}$$
$$G(h_r) = 20 \log(\frac{h_r}{3}) \qquad 3\text{m} < h_t < 10\text{m}$$



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## Hata path loss model

 $L_{50} = 69.55 + 26.16 \log f_c - 13.82 \log h_t - a(h_r) + (44.9 - 6.55 \log h_t) \log d + C(f_c)$ 



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### **Coverage area**





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## Log-normal shadowing





 $PL = \overline{PL}(d) + X_{\sigma}$ 



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## Log-normal shadowing

 $\mathbf{X} = N(0, \boldsymbol{\sigma})$ 

#### zero-mean Gaussion with standard dev. $\boldsymbol{\sigma}$

**outdoor:** σ=6-9dB

**indoor:** σ=2-12dB



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## Link budget







N

## **Multipath fading**



![](_page_20_Picture_2.jpeg)

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![](_page_20_Picture_4.jpeg)

## **Multipath effects**

![](_page_21_Figure_1.jpeg)

- Doppler spread
  - speed
  - angle of arrival

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![](_page_21_Picture_7.jpeg)

## **Delay space phenomenon**

![](_page_22_Figure_1.jpeg)

![](_page_22_Picture_2.jpeg)

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![](_page_22_Picture_5.jpeg)

## Fading

$$\Delta d \approx \lambda$$
$$\Delta \tau \approx \frac{\lambda}{c} = \frac{1}{f_c}$$
$$\Delta \theta \approx \pi$$

**RF** waves

$$s_1 = r_1 \cos \theta_1$$
  

$$s_2 = r_2 \cos \theta_2$$
  

$$s_3 = r_3 \cos \theta_3$$

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![](_page_23_Picture_6.jpeg)

![](_page_24_Figure_0.jpeg)

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![](_page_24_Picture_1.jpeg)

## **Doppler spread**

![](_page_25_Figure_1.jpeg)

![](_page_25_Picture_2.jpeg)

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![](_page_25_Picture_4.jpeg)

## **Doppler shifts**

![](_page_26_Figure_1.jpeg)

![](_page_26_Picture_2.jpeg)

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![](_page_26_Picture_5.jpeg)

# **Doppler spread**

v (km/h)	$f_{\rm c}$ (MHz)	$f_{\rm d}$ (Hz)
50	900	40
100	900	80
50	2010	90
100	2010	180

![](_page_27_Picture_2.jpeg)

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![](_page_27_Picture_4.jpeg)

![](_page_28_Figure_0.jpeg)

![](_page_28_Picture_1.jpeg)

## **Measured delay profile**

![](_page_29_Figure_1.jpeg)

![](_page_29_Picture_2.jpeg)

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![](_page_29_Picture_4.jpeg)

## Impulse response model

time-variant, linear system:  $h(t, \tau)$ 

- *t*: time variant due to motion (ms to s)
- $\tau$ : time dispersion (ns to  $\mu$ s)

filter representation:

$$y(t) = x(t) * h(t, \tau)$$

![](_page_30_Picture_6.jpeg)

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![](_page_30_Picture_8.jpeg)

## **FIR representation**

$$h_b(t,\tau) = \sum_{i=0}^{N-1} a_i(t) \exp\{-j\theta_i(t)\}\delta(\tau-\tau_i)$$

![](_page_31_Figure_2.jpeg)

 $BW_{signal} < 1/(2\Delta\tau)$  $\tau 0:$  excess delay reference $N\Delta\tau:$  maximum excess delay

![](_page_31_Picture_4.jpeg)

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![](_page_31_Picture_6.jpeg)

## **FIR representation**

![](_page_32_Figure_1.jpeg)

![](_page_32_Picture_2.jpeg)

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![](_page_32_Picture_4.jpeg)

## **Power delay profile**

 $\left|h_{b}(t,\tau)\right|^{2}$ 

measured in local area
spatial averaging (2-6m)

![](_page_33_Picture_3.jpeg)

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![](_page_33_Picture_6.jpeg)

## **Time dispersion parameters**

![](_page_34_Figure_1.jpeg)

$$\overline{\tau^2} = \frac{\sum_{k} P(\tau_k) \tau_k^2}{\sum_{k} P(\tau_k)}$$

mean excess delay:  $\overline{\tau}$ rms delay spread:  $\sigma_{\tau} = \sqrt{\overline{\tau}^2 - (\overline{\tau})^2}$ 

maximum excess delay:  $\tau$  where  $P \leq P_{max}$ 

![](_page_34_Picture_5.jpeg)

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![](_page_34_Picture_8.jpeg)

## **Time dispersion example**

![](_page_35_Figure_1.jpeg)

![](_page_35_Picture_2.jpeg)

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![](_page_35_Picture_4.jpeg)

## **Time dispersion values**

environment	f(MHz)	$\sigma_{ au}$
urban	900	10-25µs
suburban	900	200-300ns
indoor	1500	70-90ns

![](_page_36_Picture_2.jpeg)

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![](_page_36_Picture_4.jpeg)

## **Coherence bandwidth**

#### $h(t, \tau) \leftrightarrow H(f)$

#### **B\_c: \Delta f where frequencies become uncorrelated**

corr.>0.5

![](_page_37_Picture_4.jpeg)

![](_page_37_Picture_5.jpeg)

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![](_page_37_Picture_8.jpeg)

## Flat fading

#### All frequency components fade identically.

![](_page_38_Figure_2.jpeg)

![](_page_38_Figure_3.jpeg)

![](_page_38_Picture_4.jpeg)

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![](_page_38_Picture_6.jpeg)

## **Frequency-selective fading**

#### **Different frequency components fade differently.**

![](_page_39_Figure_2.jpeg)

![](_page_39_Figure_3.jpeg)

![](_page_39_Picture_4.jpeg)

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![](_page_39_Picture_6.jpeg)

# **Rayleigh fading**

- Amplitude fading
- N i.i.d. components: resultant Normally (Gaussian) distributed
- Gaussian distribution on I and Q gives Rayleigh on envelope

![](_page_40_Figure_4.jpeg)

## **Rayleigh distribution**

$$p(r) = \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) \quad (r \ge 0)$$

![](_page_41_Figure_2.jpeg)

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![](_page_41_Picture_5.jpeg)

## **Rician fading**

- Amplitude fading
- One dominant component + N i.i.d. components: resultant Rician distributed

![](_page_42_Picture_3.jpeg)

![](_page_42_Picture_4.jpeg)

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![](_page_42_Picture_6.jpeg)

## **Rician distribution**

$$p(r) = \frac{r}{\sigma^2} \exp\left(-\frac{r^2 + A^2}{2\sigma^2}\right) I_0\left(\frac{Ar}{\sigma^2}\right) \quad (A, r \ge 0)$$

A: amplitude of dominant component *I*<sub>0</sub>: zero-order Bessel function

**Rician factor:** 
$$K = \frac{A^2}{2\sigma^2}$$

![](_page_43_Picture_4.jpeg)

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![](_page_43_Picture_7.jpeg)

## **Rician distribution**

$K \rightarrow -\infty$ :	approaching Rayleigh
$K \rightarrow \infty$ :	approaching $N(A,\sigma)$

![](_page_44_Figure_2.jpeg)

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![](_page_44_Picture_5.jpeg)

## **Modeling: flat fading**

![](_page_45_Figure_1.jpeg)

![](_page_45_Figure_2.jpeg)

*a*: Rayleigh dist. *φ*: uniform (0,2π]

![](_page_45_Picture_4.jpeg)

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![](_page_45_Picture_6.jpeg)

## **Modeling: 2-ray fading**

![](_page_46_Figure_1.jpeg)

![](_page_46_Figure_2.jpeg)

![](_page_46_Picture_3.jpeg)

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![](_page_46_Picture_5.jpeg)

## **Doppler spread**

![](_page_47_Figure_1.jpeg)

![](_page_47_Picture_2.jpeg)

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![](_page_47_Picture_4.jpeg)

### **Doppler power spectrum**

![](_page_48_Figure_1.jpeg)

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![](_page_48_Picture_4.jpeg)

### **Coherence time**

$$S_D(f) \leftrightarrow h_D(t)$$

#### $T_c: \Delta t$ where samples become uncorrelated

![](_page_49_Picture_3.jpeg)

![](_page_49_Picture_4.jpeg)

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![](_page_49_Picture_6.jpeg)

## **Slow and fast fading**

#### **Fast fading:**

![](_page_50_Picture_2.jpeg)

#### **Slow fading:**

![](_page_50_Picture_4.jpeg)

![](_page_50_Picture_5.jpeg)

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![](_page_50_Picture_7.jpeg)

## Slow/fast - flat/freq-sel. fading

**Flat / frequency selective fading:** 

Echo pattern h(t, T)

Fast / slow fading:

Motion effects  $h(\mathbf{t},\tau)$ 

![](_page_51_Picture_5.jpeg)

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![](_page_51_Picture_7.jpeg)

![](_page_52_Figure_0.jpeg)

![](_page_53_Figure_0.jpeg)

## **Multipath time scales**

• Amplitude fading: 
$$dt \approx \frac{1}{f_c}$$
 (i.e.  $dt=1$ ns)  
• Time dispersion:  $dt \approx \frac{\Delta d}{c}$  (i.e.  $dt=1$ µs)  
• Doppler spread:  $dt \approx \frac{1}{f_d}$  (i.e.  $dt=10$ ms)

![](_page_54_Picture_2.jpeg)

ATION NG **Mob** 

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![](_page_54_Picture_5.jpeg)

## FOR NEXT WEEK

• Read:

Chapter 5: §5.1, 5.2 (<u>not</u> 5.2.2, 5.2.3), 5.3 (<u>not</u> 5.3.2, 5.3.3) §5.4 - 5.9 (<u>not</u> 5.7.8)

Solve problems:

Chapter 4: 4.2, 4.3, 4.5, 4.18, 4.21

![](_page_55_Picture_5.jpeg)

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![](_page_55_Picture_8.jpeg)